
Mechanical Shock and Modal Test Techniques

Course No. 142-4

APPLICATIONS The effects of shock are important in many engineering applications ranging from appliances to computers to ships to automobiles, trucks and military vehicles to high-performance aircraft and missiles. Shock is often part of the service and/or transportation environment. Military Standards such as MIL-STD-810 call for shock testing.

The possible effect of shock must be considered for almost every product that has to be shipped and handled. Care can be taken in a controlled environment but during the transportation phase the product within its package must be designed and tested to withstand the anticipated environment.

FOR WHOM INTENDED Engineers involved with dynamics and structural test applications.

Most engineers need specialized education in order to properly measure, quantize and analyze the shock environment, and to reproduce it in environmental test laboratories. This course is for test laboratory managers, engineers and technicians. It will also help quality and reliability specialists and acquisition personnel in government and military activities and contractors.

Instrumentation specialists who will measure transportation, service and laboratory shock need this course. Metrologists learn about shock calibration of accelerometers and systems. Project personnel, structure and packaging engineers learn about developmental shock testing. Product assurance and acquisition specialists learn to evaluate shock test facilities and methods, and to interpret shock test specifications.

This course is designed to serve the varied needs of scientists, engineers, aides and senior technicians. The instructor maintains good balance between practical training and theory.

BRIEF COURSE DESCRIPTION The course begins with a review of structural and dynamic theory before examining methods of measuring frequency response from the structure under test. The causes and effects of shock are reviewed in detail, including the different shock pulse shapes.

Experimental modal testing is introduced by a brief discussion of theoretical modal analysis. The single degree of freedom (SDoF) model enables us to understand the fundamental concepts of free and forced vibration, natural frequency, resonance and damping. However in MDoF systems, resonance may occur at a number of different frequencies, each of which corresponds to a different pattern or shape of the system's motion. These are known as the natural or normal modes of vibration or mode shapes. There is a differential equation of motion for each degree of freedom; a set of n simultaneous equations is needed to

mathematically describe a MDoF system. These equations are usually solved using matrix algebra.

In the experimental method of Modal Testing, the structure is excited by applying forced vibration and measuring the responses, from which the vibration modes are determined and a structural model developed. This is the reverse process to the theoretical method. Various methods of input excitation are discussed, such as shaker and impact hammer. Structural preparation and suspension methods are also examined.

A review of transducers and signal processing equipment is made before discussing analysis methods, time-domain curve fitting. Modal test philosophy including the sequence of steps and practical considerations in undertaking the test are discussed.

The tabulation of results and derivation of mode shapes and construction of spatial models (mass, stiffness and damping) are covered before discussing the application of the modal test results.

The Shock Response Spectrum (SRS) is discussed as it relates to shock measurement and testing. The course then covers shock measurements, also calibration. The relative merits of various types of shakers and shock test machines are briefly considered before covering various shock test methods, including pyrotechnic shock testing. Some typical shock test procedures and specifications are described, both military and commercial.

CERTIFICATE PROGRAMS This course is required for TTI's [Dynamic Test Specialist Certificate](#). It may be used as an elective for any of TTI's [Specialist Certificate programs](#).

RELATED COURSES See TTI courses [142, Mechanical Shock Techniques](#), and [195, Modal Analysis for Structural Validation](#), which were combined to create this course.

PREREQUISITES Prior participation in TTI's "[Fundamentals of Vibration](#)" would be helpful. Some familiarity with electrical and mechanical measurements and vibration will be helpful.

TEXT Each student will receive a [course workbook](#) containing most of the viewgraphs used in the presentation.

COURSE HOURS, CERTIFICATE AND CEUs Open courses meet seven hours per day. Upcoming presentation dates can be found on our current [open course schedule](#). Class hours/days for on-site courses can vary from 14–35 hours over 2–5 days as requested by our clients. Upon successful course completion, each participant receives a certificate of completion and one Continuing Education Unit (CEU) for every ten class hours.

For [schedules](#), [general information](#) and [registration forms](#), see TTI's web site.



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Single-Degree-of-Freedom (SDoF) and 2DoF Systems

The Single Degree of Freedom System:

Spring, k ; Mass, m Damper, c

Motion of an SDoF System

The Impulse Response Function, $h(t)$

The Frequency Response Function (FRF) • Displaying the FRF

Nyquist Plot • Structural Dynamic Relationships

Two Degrees of Freedom (2DoF) • 2DoF Frequency Response

Multiple-Degrees of Freedom (MDoF) Systems

Natural Frequencies and Mode Shapes

Modal and Frequency Matrices

Orthogonality and Normalization

Decoupling the Equations

Single Point Excitation and Response

Mode Shapes for: Cantilever; Plate • Mode Shape Animation

Some Essentials of Signal Processing

Analog to Digital (A-D) Conversion • Aliasing • FFT • DFT

Windowing for Continuous, Random and Transient Signals

System Identification Using the FFT • Signal Averaging

Coherence • Rules of Signal Processing

Time and Frequency Domain Terminology

Introduction to Shock: What is Shock? • Causes of Shock

Effects and Remedies of Shock • Natural Frequency

Single-Degree-of-Freedom Transient Response

Transient Response Problem • Free Response

Forced Response

A Closer Look at Shock: Terms used in Mechanical Shock

Input Pulse and Response of a Sprung Mass

Typical Complex Shock Pulses

Shock Pulse Shape Parameters

Haversine Shape • Classical Shock Pulse Shapes

Critical Frequency Response • Response to Shock Pulse

Background and Theory of Modal Testing

Experimental Modal Analysis (EMA) • Theoretical Modes

Experimental Examples — Ship Hull Section, Bridge Deck

The Time Domain Structural Response

The Frequency Domain

Experimental Modal Analysis (EMA) Procedure

Modal Test Planning and Set-up: Selecting a Test Procedure

Steady-State • Random • Impact • Burst Random / Chirp

Shaker Testing • Impact Testing • Response Transducers

Strain gages • Laser • Accelerometers • Charge accelerometers

Voltage Accelerometers • Voltage vs. Charge Accelerometers

Mounting Accelerometers • Transducer Selection

Meshing: Definition, Considerations

The “Pretty Picture” Approach

Fine Mesh vs. Coarser Mesh • An Interpolation Example

Practical Aspects of Marking a Mesh

Setting up the Modal Test: Support the Structure

Free Boundary • Mounting Transducers • Contact Resonance

Mounting Methods: Stud, Superglue, Beeswax, Magnet,

Mounting Base, Double-Mount

Suggestions for Making Life Easier • Setting up the Analyzer

Random Excitation • Impact Excitation

Windowing the Response

Coherence Function • Coherence Examples

Modal Parameter Extraction

Natural Frequencies, Modal Damping, and Modal Constant

Modal Interposition Using Single Mode Methods

“Quadrature” method • “Circle Fit” Method • Modal Residues

Multiple Mode Methods

Documenting Modal Test Results

Average Coherence Example • Viscous Damping Coefficients

Presenting Mode Shapes:

Deflected Shape, Undeformed & Deflected Shapes

Deflected Extremes, Arrows, Persistence

Color Rendition • Presenting Mode Shapes – Animations

The Shock Response Spectrum:

Measuring and Analyzing Shock • Mechanical Analog

Definitions • Developing SRS • SRS Maximax Values

Max. Response Spectra for Various Shock Pulse Shapes

Some Properties of the SRS • Velocity Sensitive Region

Damping and SRS • SRS Damped Spectra

Maximum Response Spectra for Linear SDof System

Designing with SRS • Absolute and Relative Deflection SRS

The Use of the SRS in Shock Testing

Shock Test Specification—Required Spectrum and Allowable

Tolerances

Types of Shock Spectrum Analyzers (SSA)

Measurement of Shock:

Force Sensors • Load Cell Characteristics

Motion: Displacement Trackers

Characteristics of Motion Trackers • High speed Photography

Electro-Magnetic Induction

Motion—Velocity Sensors and Accelerometers

Seismic Transducers • Seismic Transducer Characteristics

Pendulum Calibration

Dynamic Calibration of Motion Sensors

Cabling • Accelerometer Attachment

Accelerometer Quick-Check Calibration

Accelerometer Loading Effect

Shock Testing: Types of Mechanical Shock Testing

Impulse Shock Test

Shock Pulse — Acceleration, Velocity and Displacement

Drop Test Machines • Navy Impact Machines

The “Light-Weight” Shock Tester

High-Amplitude, High-Frequency Impact Transient Simulators

Impact Shock Simulators • MIPS Table

Programmable Systems • Mid-Frequency Transients

Shakers : Electrodynamic, Hydraulic, Piezoelectric

Shaker Technologies—Stroke vs. Frequency Range

Generating Prescribed Pulses • Optimized Tailoring

Generation of Oscillatory Transients

Decaying Harmonic Acceleration

Shaker Optimized Cosine (SHOC) pulses

Least Favorable Response

Simulating the Damage from a PyroShock

Pyrotechnic Shock • Rupture Energy Fixture

More Realistic Pyroshock Arrangements

Shock Testing Problem Areas • Data as We See It

What Our System Has to Handle

Drop Machines • Pendulum Type Shock Machine

Free-Fall Shock Machine • Drop Testing Machine

Typical Shock Test Specifications

Summary • Final Review

Award of certificates for successful completion

